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EXPONENTIAL MAPPING FOR LIE GROUPOIDS

BY

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0. Introduction. Lie groupoids have appeared in many problems of differential geometry of higher order, e.g., in the theories of connections of higher order, *G*-structures of higher order, pseudogroups, and in some theory of differential equations. Originally (see [5]), Lie groupoids were associated with principal fibre bundles. Ngo Van Que [27] formulated in 1967 a precise abstract definition of these objects (see also [7] and [18]). The development of the general theory of Lie groupoids can be found in the papers of Pradines [22]-[26] and Kumpera [11], [12], and also in [3], [4], [8], [15]-[17], [21], [31]-[34].

In [11] an exponential mapping was defined. This paper is devoted to a closer examination of this notion.

A Lie groupoid (see [27]) is a collection

$$(0.1) \qquad \Phi = (\Phi, (a, \beta), M, \cdot)$$

in which

(i) Φ and M are smooth (i.e., of class C^{∞}) manifolds with countable bases, M being a connected manifold;

(ii) $\alpha: \Phi \to M$ and $\beta: \Phi \to M$ are surmersions (i.e., submersions plus onto);

(iii) $: D \to \Phi$, where $D = \{(z, z') \in \Phi \times \Phi : a(z) = \beta(z')\}$, is a partial multiplication which satisfies

(a) β(z ⋅ z') = β(z) and a(z ⋅ z') = a(z') if (z, z') ∈ D and ⋅(z, z') = z ⋅ z',
(b) for every point x ∈ M there exists an element l_x ∈ Φ such that a(l_x) = β(l_x) = x and z ⋅ l_x = z if a(z) = x and l_x ⋅ z = z if β(z) = x,

(c) for every element $z \in \Phi$ there exists an element $z^{-1} \in \Phi$ such that $z \cdot z^{-1} = l_y$, where $y = \beta(z)$, and $z^{-1} \cdot z = l_x$, where $w = \alpha(z)$;

(iv) the condition of transitivity holds, which means that (α, β) : $\Phi \to M \times M$ is surjective;

(v) the mapping $^{-1} = (\Phi \ni z \mapsto z^{-1} \in \Phi)$ is smooth;

(vi) for every smooth manifold W and for every two smooth mappings $f, g: W \to \Phi$ such that $\alpha \circ f = \beta \circ g$, the mapping

 $f \cdot g = (W \ni z \mapsto f(z) \cdot g(z) \in \Phi)$

is smooth.

If $\boldsymbol{\Phi} = (\boldsymbol{\Phi}, (a, \boldsymbol{\beta}), M, \cdot)$ is a Lie groupoid (shortly, L.g.), then $\boldsymbol{\Phi}$ is called a space of the groupoid $\boldsymbol{\Phi}$, M is said to be a manifold of units, a and $\boldsymbol{\beta}$ are called mappings "source" and "target".

The set $\Phi_{(x,x)}$ of those elements h, belonging to the space of a Lie groupoid $\boldsymbol{\Phi}$, for which $\alpha(h) = \beta(h) = x$ is called the *isotropy group* of $\boldsymbol{\Phi}$ over x. It is a Lie group [27]. For every Lie groupoid $\boldsymbol{\Phi}$ and every x belonging to M (i.e., to a manifold of the units) a principal fibre bundle

$$\boldsymbol{\Phi}_x = (\Phi_x, M, \gamma, \Phi_{(x,x)}, \cdot)$$

is determined in the following way [27]: The set Φ_x consists of all elements $h \in \Phi$ such that ah = x (i.e., a(h) = x). Φ_x is a submanifold of Φ . The projection $\gamma: \Phi_x \to M$ is equal to $\beta | \Phi_x$. The action of the Lie group $\Phi_{(x,x)}$ on Φ_x is determined by the formula $\cdot(h, g) = h \cdot g$, where $h \in \Phi_x, g \in \Phi_{(x,x)}$.

A Lie group is a Lie groupoid with a one-element manifold of the units. A typical example is the Lie groupoid $\pi^k(M)$ of all invertible jets of the k-th order of a manifold M, where $\alpha(j_x^k f) = x$, $\beta(j_x^k f) = f(x)$, and $j_{g(x)}^k f \cdot j_x^k g = j_x^k(f \circ g)$ (see [6], [13], and [14]).

An element $h \in \Phi$ such that ah = x and $\beta h = y$ will be denoted by

$$x \xrightarrow{h} y$$

1. Lie algebroid of a Lie groupoid. Let $\Phi = (\Phi, (\alpha, \beta), M, \cdot)$ be an L.g. The diffeomorphism

$$\Phi_h = (\Phi_{\beta h} \ni g \mapsto g \cdot h \in \Phi_{ah})$$

is called a right translation by the element $h \in \Phi$ (see [11]). The vector field ξ on an open set $\Omega \subset \Phi$ is called right-invariant (shortly, r-i) if ξ is a-vertical (i.e., $a_* \xi_g = 0, g \in \Omega$) and if ξ is invariant with respect to all right translations by elements $h \in \Phi$ (i.e., $\xi_{gh} = (\Phi_h)_{*g}(\xi_g), g \in \Omega$ and $gh \in \Omega$). See also [19].

Example. Let X be a vector field on an open subset U of a manifold N and let X be generated by a local one-parameter group of diffeomorphisms f_t . Then the family f_t^k determined on the open set $\beta^{-1}[U] \subset \pi^k(N)$ by the formula

$$j_t^k Y = j_{\beta Y}^k f_t \cdot Y, \quad Y \in \beta^{-1}[U],$$

is a local one-parameter group of diffeomorphisms. It generates a vector field X^k which is r-i (see [30]).

The mappings $\sigma: U \to \Phi$, where U is an open set in M such that $\beta \circ \sigma = \operatorname{id}_U$ and $a \circ \sigma: U \to M$ is a diffeomorphism onto an open subset of M, are called *a*-admissible β -sections.

The mapping $\varphi: a^{-1}[U] \to a^{-1}[U']$ defined by the formula

$$\varphi(g) = g \cdot \sigma(ag), \quad g \in a^{-1}[U],$$

where $\sigma: U \to \Phi$ is an a-admissible β -section such that $a \circ \sigma[U] = U'$, is called a right translation by the section σ (see [11]).

THEOREM 1.1. If ξ is an r-i vector field on an open set $\Omega \subset \Phi$, then there exists exactly one r-i vector field ξ' on $\Omega' = \beta^{-1}[\beta[\Omega]]$ such that the restriction of ξ' to Ω is equal to ξ . If ξ is smooth, then so is ξ' .

Proof. The existence and uniqueness of ξ' are evident. Assume that ξ is smooth. We take an arbitrary element $x' \xrightarrow{h} y$ belonging to $\beta^{-1}[\beta[\Omega]]$ and an element $x \xrightarrow{g} y$ belonging to Ω ($\beta h = \beta g = y$). Let $\varphi: a^{-1}[U] \rightarrow a^{-1}[U']$ be a right translation by an *a*-admissible β -section $\sigma: U \rightarrow \Phi$ for which $x \in U$ and $\sigma(x) = g^{-1} \cdot h$. We take $\Theta = \Omega \cap a^{-1}[U]$ and $\Theta' = \varphi[\Theta]$. Then $h \in \Theta', g \in \Theta$ and, clearly, $\xi' | \Theta' = (\varphi | \Theta)_*(\xi | \Theta)$, which completes the proof.

Let us consider the vector bundle (see [24]) $i^*(T^a\Phi)$, i.e., first we take the vector subbundle $T^a\Phi \subset T\Phi$ of the tangent bundle $T\Phi$, consisting of all *a*-vertical vectors, and next we pull it back by the imbedding $i = (M \ni x \mapsto l_x \in \Phi)$.

The r-i field ξ on an open set $\Omega \subset \Phi$ determines a cross-section $\xi_{\mathfrak{a}}$ of $i^*(T^{\mathfrak{a}}\Phi)$ over $\beta[\Omega]$ by the formula

$$(\xi_0)_x = (\Phi_{k-1})_{*h}(\xi_h), \quad x \in \beta[\Omega], h \in \Omega, \text{ and } \beta h = x.$$

The correctness of that formula follows from $(\xi_0)_x = \xi'(l_x)$ (for ξ' see Theorem 1.1). If ξ is smooth, then so is ξ_0 .

THEOREM 1.2. Every cross-section η of $i^*(T^a \Phi)$ over an open set $U \subset M$ can be extended uniquely to an r-i vector field η' on $\beta^{-1}[U]$. If η is smooth, then so is η' .

Proof. We take a cross-section η of $i^*(T^a \Phi)$ over an open set $U \subset M$. It determines a vector field η' on $\beta^{-1}[U] \subset \Phi$ by the formula

$$\eta'(h) = (\Phi_h)_{*l_{sh}}(\eta(\beta h)), \quad h \in \beta^{-1}[U].$$

Clearly, η' is r-i. Let η be a smooth cross-section. To prove the theorem it suffices to show that η' is smooth in a neighbourhood of every unit l_x , $x \in U$.

Fix the unit $l_{x_0}, x_0 \in U$, and take a coordinate system $\overline{x} = (\overline{x}_1, \dots, \overline{x}_n)$ of the manifold M in the domain $D_{\overline{x}} \ni x_0$ and a coordinate system

$$\hat{x} = (\hat{x}_1, \dots, \hat{x}_n, \hat{x}_{n+1}, \dots, \hat{x}_{n+m}, \hat{x}_{n+m+1}, \dots, \hat{x}_{2n+m})$$

of the manifold Φ in the domain $D_{\hat{x}}$ such that

- (a) $l_{x_0} \in D_{\hat{x}}$,
- (b) $\alpha[D_{\hat{x}}] \subset D_{\bar{x}}, \ \beta[D_{\hat{x}}] \subset D_{\bar{x}},$
- (c) $(\hat{x}_1, \ldots, \hat{x}_n) = \overline{x} \circ \beta | D_{\hat{x}},$
- (d) $(\hat{x}_{n+m+1}, \ldots, \hat{x}_{2n+m}) = \overline{x} \circ a | D_{\hat{x}}.$

Clearly, there exists a neighbourhood $V \subset D_{\hat{x}}$ of l_{x_0} such that $\tau, \sigma \in V$ implies $\tau \cdot \sigma \in D_{\hat{x}}$. If $\sigma \in V$, then for i = 1, ..., 2n + m

$$\begin{split} (\eta')_{\sigma}(\hat{x}_{i}) &= (\varPhi_{\sigma})_{*\beta\hbar}(\eta_{\beta\hbar})(\hat{x}_{i}) \\ &= \eta_{\beta\sigma}(\hat{x}_{i} \circ \varPhi_{\sigma}) = \eta_{\beta\sigma}(\varPhi_{\beta\sigma} \ni \tau \mapsto \hat{x}_{i}(\tau \cdot \sigma) \in R) \end{split}$$

We take the imbedding

$$egin{aligned} l &= \left(R^n imes R^m imes R^n imes R^n imes R^{2n+m} imes R^{2n+m}
ight), \ & (a, b, c, d, e) \mapsto ig((a, b, c), (c, d, e)ig), \end{aligned}$$

and we put

$$W = l^{-1} \left[\hat{x}[V] imes \hat{x}[V]
ight] \subset R^{3n+2m}.$$

W is an open set containing the point

$$(\hat{x}_1(l_{x_0}), \ldots, \hat{x}_{2n+m}(l_{x_0}), \hat{x}_{n+1}(l_{x_0}), \ldots, \hat{x}_{2n+m}(l_{x_0})).$$

There exist smooth functions $f_i: W \to R, i = 1, ..., 2n + m$, for which $\hat{x}_i(\tau \cdot \sigma) = f_i(\hat{x}_1(\tau), ..., \hat{x}_{n+m}(\tau), \hat{x}_1(\sigma), ..., \hat{x}_{2n+m}(\sigma)), \quad i = 1, ..., 2n + m,$ where $\tau, \sigma \in V$ and $\tau \cdot \sigma$ is defined. Hence

$$\begin{aligned} (\eta')_{\sigma}(\hat{x}_{i}) &= \eta_{\beta\sigma} \Big(f_{i} \big(\hat{x}_{1}(\cdot), \ldots, \hat{x}_{n+m}(\cdot), \hat{x}_{1}(\sigma), \ldots, \hat{x}_{2n+m}(\sigma) \big) \Big) \\ &= \sum_{j=1}^{n+m} \eta_{\beta\sigma}(\hat{x}_{j}) \cdot f_{i|j} \big(\hat{x}_{1}(l_{\beta\sigma}), \ldots, \hat{x}_{n+m}(l_{\beta\sigma}), \hat{x}_{1}(\sigma), \ldots, \hat{x}_{2n+m}(\sigma) \big). \end{aligned}$$

Finally, to complete the proof it suffices to see that the function $V \ni \sigma \mapsto n_{e_{\sigma}}(\hat{x}_{\cdot}), \quad i = 1, \dots, n+m.$

$$V \ni \sigma \mapsto f_{i|j}\left(\hat{x}_1(l_{\beta\sigma}), \ldots, \hat{x}_{n+m}(l_{\beta\sigma}), \hat{x}_1(\sigma), \ldots, \hat{x}_{2n+m}(\sigma)\right),$$
$$i = 1, \ldots, 2n+m, \ j = 1, \ldots, n+m,$$

are smooth.

From Theorem 1.2 it follows that if ξ is an r-i vector field on an open set $\Omega \subset \Phi$, then for any point $g \in \Omega$ there exists a globally defined r-i vector field η on Φ such that $\xi | \Theta = \eta | \Theta$ for an open set $\Theta \subset \Omega$, where $g \in \Theta$.

We shall continue to assume that the r-i vector fields under consideration are smooth. Let ξ and η be some r-i vector fields on an open set $\beta^{-1}[U]$, $U \subset M$. Then the following statements are true:

(i) The Poisson bracket $[\xi, \eta]$ is also an r-i vector field.

(ii) If f belongs to $C^{\infty}(M | U)$, then the vector field $(f \circ \beta) \cdot \xi$ is also r-i and we have

 $(f \circ \beta) \cdot \xi = (f \cdot \xi_0)', \quad [\xi, (f \circ \beta) \cdot \eta] = (f \circ \beta) [\xi, \eta] + (\beta_* \xi) (f) \cdot \eta,$

where ξ_0 is a cross-section of $i^*(T^a \Phi)$ over U determined by the formula $(\xi_0)_x = \xi(l_x), x \in U$ (for $(f \cdot \xi_0)'$ see Theorem 1.2).

(iii) ξ is β -related to exactly one vector field X on U. If we denote by $\tilde{\beta}_*$ the morphism

$$i^*(T^a \Phi) \ni v \mapsto \beta_*(v) \in TM$$
,

then X is equal to $\tilde{\beta}_* \circ \xi_0$ and it is denoted by $\beta_* \xi$.

(iv) The vector space of all smooth global cross-sections of $i^*(T^a\Phi)$, namely $C^{\infty}(i^*(T^a\Phi))$ with bracket [],]] defined by $[\![\xi,\eta]\!] = [\xi',\eta']_0$, is an R-Lie algebra. This bracket has the property

$$\llbracket \xi, f \cdot \eta \rrbracket = f \cdot \llbracket \xi, \eta \rrbracket + (\beta_* \xi)(f) \cdot \eta.$$

(v) The morphism $\tilde{\beta}_*$ has the following properties:

(a) $\tilde{\beta}_*$ is an epimorphism,

(b) $C^{\infty}(\tilde{\beta}_*): C^{\infty}(i^*(T^a \Phi)) \to C^{\infty}(TM)$ is an R-Lie algebra homomorphism.

A Lie algebroid (shortly, L.a.) is a collection

$$\boldsymbol{A} = (\boldsymbol{A}, [\![,]\!], \boldsymbol{\gamma})$$

in which

(1) A is a vector bundle over any manifold M;

(2) $[\![,]\!]: C^{\infty}(A) \times C^{\infty}(A) \to C^{\infty}(A)$ is a mapping such that $(C^{\infty}(A), [\![,]\!])$ is a Lie algebra (over R);

(3) $\gamma: A \to TM$ is an epimorphism of the vector bundles;

(4) if $\eta, \mu \in C^{\infty}(A)$ and $f \in C^{\infty}(M)$, then

 $\llbracket \eta, f \cdot \mu \rrbracket = f \cdot \llbracket \eta, \mu \rrbracket + (\gamma \circ \eta)(f) \cdot \mu;$

(5) $C^{\infty}(\gamma): C^{\infty}(A) \to C^{\infty}(TM)$ is an *R*-Lie algebra homomorphism. Thus an arbitrary L.g. $\Phi = (\Phi, (\alpha, \beta), M, \cdot)$ determines any object

(1.1) $(i^*(T^a\Phi), [,], \tilde{\beta}_*)$

which is a Lie algebroid (see [24]).

This definition is almost identical with that of Pradines [24]. It differs in that Pradines does not require for the morphism γ to be an epimorphism. The reason is the fact that Pradines associates such an object with an

object more general than L.g., namely with the differential one (see also [1], [2], [9], [10], [20]).

Example. The L.a. of the L.g. $\pi^k(M)$ is isomorphic to

$$(J^k(TM), [,], \tilde{\beta}),$$

where

(i) $J^k(TM)$ is the vector bundle of the k-th order jets of vector fields of M,

(ii) $\tilde{\beta} = (J^k(TM) \ni j_x^k \Theta \mapsto \Theta(x) \in TM),$

(iii) $[\![],]\!]: C^{\infty}(J^k(TM)) \times C^{\infty}(J^k(TM)) \to C^{\infty}(J^k(TM))$ is the only mapping for which $(C^{\infty}(J^k(TM)), [\![],]\!]$ is a Lie algebra and

$$\llbracket \sigma, f \cdot \eta \rrbracket = f \llbracket \sigma, \eta \rrbracket + (\hat{\beta}\sigma)(f) \cdot \eta$$

for $\sigma, \eta \in C^{\infty}(J^k(TM))$ and $f \in C^{\infty}(M)$.

Investigations of such objects were carried out by Libermann [13], [14].

Example. The L.a. of the trivial L.g. $M \times G \times M$ is a collection $(TM \times \mathfrak{g}, [\![,]\!], \tilde{\beta})$, where

(i) g is the Lie algebra of the Lie group G;

(ii) $TM \times g$ is the vector bundle over M in which a fibre over $x \in M$ is equal to $T_xM \times g$;

(iii) $\tilde{\beta} = (TM \times g \ni (v, u) \mapsto v \in TM);$

(iv) if X, X' are two vector fields on M and h, h': $M \to g$ are two smooth mappings, then

 $\llbracket (X,h), (X',h') \rrbracket = (\llbracket X,X' \rrbracket, \mathscr{L}_X h' - \mathscr{L}_{X'} h + \llbracket h,h' \rrbracket).$

A smooth mapping $F: \Phi | \Omega \to \Phi'$, where Φ and Φ' are spaces of the L.g.'s

(1.2)
$$\boldsymbol{\Phi} = \left(\boldsymbol{\Phi}, (a, \beta), \boldsymbol{M}, \cdot \right), \quad \boldsymbol{\Phi}' = \left(\boldsymbol{\Phi}', (a', \beta'), \boldsymbol{M}, \cdot' \right),$$

and Ω contains all units $l_x, x \in M$, is called a *local homomorphism* from Φ into Φ' if

(i) $\alpha' \circ F = \alpha | \Omega, \beta' \circ F = \beta | \Omega,$

(ii) $z, z', z \cdot z' \in \Omega$ implies $F(z \cdot z') = F(z) \cdot F(z')$.

If $\Omega = \Phi$, then the local homomorphism is called a homomorphism from Φ into Φ' (see [27]).

Let $F: \Phi | \Omega \to \Phi'$ be a local homomorphism from Φ into Φ' . It is easy to see that the mapping

$$ilde{F}_* = ig(i^*(T^a arPhi)
i v \mapsto F_*(v) \in i'^*(T^a arPhi') ig)$$

has the following properties:

(i) \tilde{F}_* is a morphism of the vector bundles;

(ii) if ξ is a cross-section of $i^*(T^a \Phi)$, then ξ' and $(\tilde{F}_* \circ \xi)'$ are *F*-related (see Theorem 1.2);

(iii) $C^{\infty}(\tilde{F}_*)$ is a Lie algebra homomorphism;

(iv) the diagram



is commutative.

From these properties we infer that the following definition is justified [11], [24]:

Definition 1.1. Let

 $A = (A, [,], \gamma)$ and $A' = (A', [,]', \gamma')$

be arbitrary L.a.'s over a manifold M. A morphism $H: A \to A'$ of the vector bundles is called an L.a. morphism if $C^{\infty}(H): C^{\infty}(A) \to C^{\infty}(A')$ is a Lie algebra homomorphism and the following diagram is commutative:



The assignment of the L.a. (1.1) to an L.g. (0.1) and of the L.a. homomorphism \tilde{F}_* to an L.g. homomorphism F is a covariant functor from the category of L.g. into the one of L.a. It is called the *Lie functor for L.g.*

2. Groupoid of β -admissible *a*-sections $\Gamma_{a,\text{loc}}(M, \Phi)$. The L.g. Φ defined by (0.1) determines another very important object, namely the groupoid of β -admissible *a*-sections (see [11] and [12]) $\Gamma_{a,\text{loc}}(M, \Phi)$. It consists of such local sections $\sigma: M | U \to \Phi$ of the surmersion $a: \Phi \to M$ for which U and $U' = \beta \circ \sigma[U] \subset M$ are open sets and $\beta \circ \sigma: M | U \to M | U'$ is a diffeomorphism. The element $\sigma(x)$ will often be denoted by σ_x , and the topology of M by TopM. We define the mappings

$$a, b: \Gamma_{a, \text{loc}}(M, \Phi) \to \text{Top}M$$

by the formulas

$$a(\sigma) = D_{\sigma}, \quad b(\sigma) = \beta \circ \sigma [D_{\sigma}],$$

where $\sigma: M|D_{\sigma} \to \Phi$ (i.e., D_{σ} is the domain of the σ) for σ belonging to $\Gamma_{a,\text{loc}}(M, \Phi)$. The multiplication $\tau \cdot \sigma$ for $\sigma: M|U \to \Phi$ and $\tau: M|U' \to \Phi$ belonging to $\Gamma_{a,\text{loc}}(M, \Phi)$ is defined if $\beta \circ \sigma[U] = U'$, and we have

$$\tau \cdot \sigma = (U \ni x \mapsto \tau_{\beta(\sigma_x)} \cdot \sigma_x \in \Phi).$$

The collection $(\Gamma_{a,\text{loc}}(M, \Phi), (a, b), \text{Top}M, \cdot)$ is a groupoid. It is called a groupoid of β -admissible a-sections. The isotropy group over the unit M of this groupoid is denoted by $\Gamma_a(M, \Phi)$. It is easy to find that there exists a natural isomorphism between the groupoid $\Gamma_{a,\text{loc}}(M, \Phi)$ and the groupoid of local right translations of Φ (see [11]).

Let $\boldsymbol{\Phi}$ be an arbitrary L.g. defined by (0.1). For each cross-section $\boldsymbol{\xi}$ of $i^*(T^a \boldsymbol{\Phi})$ the r-i vector field generated by $\boldsymbol{\xi}$ is denoted by $\boldsymbol{\xi}'$ (see Theorem 1.2). Every integral curve γ of $\boldsymbol{\xi}'$ lies in $\boldsymbol{\Phi}_x$ for some point $x \in M$, namely if γ passes through h, then γ lies in $\boldsymbol{\Phi}_{ah}$.

Let ξ be an arbitrary fixed global cross-section of $i^*(T^a \Phi)$. It is easy to see that the following statements are true:

(i) If z, z' belong to Φ , $z \cdot z'$ is defined, and γ is an integral curve of ξ' passing through z, then $\gamma' = \Phi_{z'} \circ \gamma$ is also an integral curve of ξ' and it passes through $z \cdot z'$.

(ii) We take a certain point $x_0 \in M$ and

$$\varphi\colon \Omega' \times I_s \to \Phi,$$

a local one-parameter group of diffeomorphisms (shortly, l.o-p.g.d.), which generates ξ' on an open set $\Omega' \subset \Phi$ containing l_{x_0} , $I_{\varepsilon} = (-\varepsilon, \varepsilon)$.

Then

(a) $z, z', z \cdot z' \in \Omega'$ imply $\varphi_t(z \cdot z') = \varphi_t(z) \cdot z', t \in I_{\varepsilon};$

(b) $z \in \Omega'$ and $l_{\beta z} \in \Omega'$ imply $\varphi_t(z) = \varphi_t(l_{\beta z}) \cdot z, t \in I_{\varepsilon};$

(c) if $l_x \in \Omega'$, $s \in I_s$, $l_{\beta(\varphi_s(l_x))} \in \Omega'$, then for every $t \in I_s$ such that $t+s \in I_s$ we have

$$\varphi_{t+s}(l_x) = \varphi_t(l_{\beta(\varphi_s(l_x))}) \cdot \varphi_s(l_x).$$

THEOREM 2.1. Let ξ belong to $C^{\infty}(i^*(T^a \Phi))$. For every point $x \in M$ there exist a neighbourhood $U \subset M$ of x, a number $\varepsilon > 0$, and an l.o-p.g.d.

(2.1)
$$\varphi' \colon \beta^{-1}[U] \times I_{\bullet} \to \Phi$$

which generates ξ' on $\beta^{-1} \lceil U \rceil$.

Proof. Let us take an arbitrary fixed point $x \in M$ and an l.o-p.g.d. $\varphi: \Omega \times I_s \to \Phi$ which generates ξ' on the open set $\Omega \subset \Phi$ containing the unit l_x . Put $U = i^{-1}[\Omega]$. By (ii) the mapping φ' must be defined by

$$\varphi'(z,t) = \varphi(l_{\beta z},t) \cdot z, \quad z \in \beta^{-1}[U], \ t \in I_{\bullet}.$$

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It suffices to show that φ' is an l.o-p.g.d. which generates $\xi'|\beta^{-1}[U]$. By the above it is easy to find that

(a) $\varphi'(z, 0) = z, z \in \beta^{-1}[U];$

(b) $\varphi'_{t+s}(z) = \varphi'_t(\varphi'_s(z)), \ z, \varphi'_s(z) \in \beta^{-1}[U], \ s, t, s+t \in I_s;$

(c) φ' generates $\xi' | \beta^{-1} [U]$.

To complete the proof it remains to see that $\varphi'(\cdot, t), t \in I_s$, is a diffeomorphism.

Let φ' be an l.o-p.g.d. which generates ξ' on $\beta^{-1}[U]$, where ξ is a cross-section of the vector bundle $i^*(T^{\alpha}\Phi)$ over the open set $U \subset M$.

Put

$$\operatorname{Exp}(t,\,\xi)=\varphi_t'\circ i\,|\,U.$$

The mapping $\operatorname{Exp}(t, \xi)$: $M | U \to \Phi$ is an *a*-section. It is easy to find that

(i) the mapping

$$\psi = (U \times I_{\varepsilon} \ni (y, t) \mapsto (\beta \circ \operatorname{Exp}(t, \xi))(y) \in M)$$

is an l.o-p.g.d. which generates $\beta_* \xi'$;

(ii) $\text{Exp}(t, \xi)$ is a β -admissible α -section, i.e.

$$\operatorname{Exp}(t,\,\xi)\in \Gamma_{a,\operatorname{loc}}(M,\,\boldsymbol{\Phi});$$

(iii) if $U' = \psi_t[U]$, then

$$\varphi'_t \colon \Phi|\beta^{-1}[U] \to \Phi|\beta^{-1}[U'], \quad t \in I_{\varepsilon},$$

are left translations.

The mapping $S: I_s \to \Gamma_{a,\text{loc}}(M, \Phi)$ is called a *local smooth one-par* ameter subgroup (shortly, l.s.o-p.s.) of the groupoid $\Gamma_{a,\text{loc}}(M, \Phi)$ on th open set $U \subset M$ ([11], [12]) if

(i) $S_t := S(t)$ is defined on the set U;

- (ii) the mapping $\hat{S} = (U \times I_s \ni (x, t) \mapsto S_t(x) \in \Phi)$ is smooth;
- (iii) $S_0 = i | U;$
- (iv) $s, t, s+t \in I_s$ and $x, \beta \circ S_s(x) \in U$ imply

$$S_{s+t}(x) = S_t(\beta \circ S_s(x)) \cdot S_s(x).$$

THEOREM 2.2. (a) If ξ is a local cross-section of $i^*(T^a\Phi)$ over an open set $U \subset M$, and φ' is an l.o-p.g.d. (2.1) which generates ξ' , then

$$S = (I_s \ni t \mapsto \operatorname{Exp}(t, \, \xi) \in \Gamma_{a, \operatorname{loc}}(M, \, \Phi))$$

is an l.s.o-p.s. of $\Gamma_{a,\text{loc}}(M, \Phi)$ over U. (In this case S is said to be generated by ξ .)

(b) Conversely, every l.s.o-p.s. of $\Gamma_{a,\text{loc}}(M, \Phi)$ over an open set $U \subset M$ is generated by exactly one cross-section of $i^*(T^a\Phi)$ over U.

Proof. (a) is evident.

(b) Let S be an l.s.o-p.s. of $\Gamma_{\alpha,\text{loc}}(M, \Phi)$ over an open set $U \subset M$. The uniqueness of ξ which generates S follows from the equality

(2.2)
$$\xi(x) = \left(S_{(\cdot)}(x)\right)_{*0} \left(\frac{\partial}{\partial t}\Big|_{0}\right), \quad x \in U.$$

We take the cross-section defined by (2.2). It is easy to see that the mapping

$$\varphi' = \left(\beta^{-1}[U] \times I_s \ni (z, t) \mapsto S_t(\beta z) \cdot z \in \Phi\right)$$

is an l.o-p.g.d. which generates ξ' . The above considerations prove that ξ' is smooth, and so is ξ . Now we see that

 $\left(\mathrm{Exp}\,(t,\,\xi)\right)(x)\,=\,\varphi'(l_x,\,t)\,=\,S_t(x)\,,\quad x\in U\,.$

A vector field on a manifold is called *complete* if it is globally defined and generated by a global one-parameter group of diffeomorphisms (shortly, g.o-p.g.d.). An r-i vector field η on an L.g. $\boldsymbol{\Phi}$ defined by (0.1) is complete if and only if the vector field $\beta_*\eta$ is complete on the manifold M(see [11] and [12]).

A cross-section ξ of $i^*(T^a \Phi)$ is called *complete* if ξ' is complete on Φ .

An l.s.o-p.s. of $\Gamma_{a,loc}(M, \Phi)$ is called a global smooth one-parameter subgroup (shortly, g.s.o-p.s.) of the group $\Gamma_a(M, \Phi)$ if it is over M and is defined on R.

A mapping $S: R \to \Gamma_a(M, \Phi)$ is a g.s.o-p.s. of $\Gamma_a(M, \Phi)$ if and only if (i) the mapping $\hat{S} = (M \times R \ni (x, t) \mapsto S(t)(x) \in \Phi)$ is smooth;

(ii) S is a homomorphism of the additive group R into $\Gamma_a(M, \Phi)$.

If ξ is a complete cross-section of $i^*(T^a \Phi)$, then

 $S = (R \ni t \mapsto \operatorname{Exp}(t, \xi) \in \Gamma_a(M, \Phi))$

is a g.s.o-p.s. of $\Gamma_a(M, \Phi)$, and

(i) $(S(\cdot)(x))_{*0}((\partial/\partial t)|_0) = \xi(x), x \in M,$

(ii) $\beta \circ S$ is a g.o-p.g.d. which generates $\beta_* \xi$.

Every g.s.o-p.s. of $\Gamma_a(M, \Phi)$ is generated by exactly one complete crosssection of $i^*(T^a\Phi)$.

3. Exponential mapping for Lie groupoids. We denote by $C_0^{\infty}(i^*(T^a \Phi))$ the set of all global cross-sections ξ of $i^*(T^a \Phi)$ such that $\beta_* \xi$ has a compact support. They are complete.

The mapping

$$\operatorname{Exp}_{\boldsymbol{\Phi}} = \left(C_0^{\infty} \left(i^*(T^a \boldsymbol{\Phi}) \right) \ni \boldsymbol{\xi} \mapsto \operatorname{Exp}\left(1, \, \boldsymbol{\xi} \right) \in \Gamma_a(M, \, \boldsymbol{\Phi}) \right)$$

is called an *exponential mapping on the L.g.* $\boldsymbol{\Phi}$ defined by (0.1) (see [11], [27], and [28]).

For a cross-section $\xi \in C_0^{\infty}(i^*(T^a \Phi))$ and a number $s \in R$ the equality $\operatorname{Exp}(1, s\xi) = \operatorname{Exp}(s, \xi)$ holds.

THEOREM 3.1. Let $F: \Phi | \Omega \to \Phi'$ be a local homomorphism from Φ into Φ' defined by (1.2). Assume that x_0 is an arbitrary point in M, $\xi \in C_0^{\infty}(i^*(T^a \Phi))$ a cross-section, and $\varepsilon > 0$ a number such that the relation

 $(\operatorname{Exp}_{\phi} t\xi)(x_0) \in \Omega$

holds for every $t \in I_{1+\varepsilon}$. Then there exist a number ε' $(0 < \varepsilon' \leq \varepsilon)$ and a neighbourhood U of x_0 such that

(i) $(\operatorname{Exp}_{\phi} t\xi)(x) \in \Omega$ for $x \in U$ and $|t| < 1 + \varepsilon'$,

(ii) $(\operatorname{Exp}_{\Phi'}(F_*\circ\xi))(x) = F((\operatorname{Exp}_{\Phi}\xi)(x))$ for $x \in U$.

Proof. Since $\tilde{\beta}'_* \circ (F_* \circ \xi)(x) = \tilde{\beta}_* \circ \xi(x)$, we have

 $\tilde{F}_* \circ \xi \in C_0^\infty(i'^*(T^a \Phi')).$

Put

$$S(t) = \operatorname{Exp}_{\phi} t \xi.$$

 $\hat{S}^{-1}[\Omega]$ is an open subset of $M \times R$ containing $\{x_0\} \times I_{1+\epsilon}$. It is easily seen that there exist a neighbourhood U of x_0 and a number ϵ' $(0 < \epsilon' \leq \epsilon)$ such that

$$U \times I_{1+\varepsilon'} \subset \hat{S}^{-1}[\Omega].$$

For an arbitrary point $(x, t) \in U \times I_{1+s'}$ we have

$$(\operatorname{Exp}_{\varphi} t\xi)(x) = \hat{S}(x,t) \in \Omega.$$

Hence the mapping

$$S' = (I_{1+s'} \ni t \mapsto F \circ ((\operatorname{Exp}_{\varPhi} t\xi) | U) \in \Gamma_{a, \operatorname{loc}}(M, \varPhi))$$

is an l.s.o-p.s. of $\Gamma_{a,\text{loc}}(M, \Phi)$ over U, which is generated by $(\tilde{F}_* \circ \xi) | U$. Therefore, equality (ii) holds.

Let us take the cross-sections $\xi_1, \ldots, \xi_m \in C_0^{\infty}(i^*(T^a \Phi))$ which are a basis of $i^*(T^a \Phi)$ over $U \subset M$. The r-i vector fields $\xi'_1 | \Phi_x, \ldots, \xi'_m | \Phi_x$ are a basis of $T(\Phi_x)$ over $\Phi_x \cap \beta^{-1}[U]$ for an arbitrary point $x \in M$. A basic property of the exponential mapping is given in the sequel.

THEOREM 3.2. For each point $x_0 \in U$ there exist open neighbourhoods $U_m \subset \mathbb{R}^m$ of 0 and $U' \subset U$ of x_0 such that the mapping

$$\overline{\mathrm{Exp}}_{\varPhi} = \left(U_m \times U' \ni (a^1, \ldots, a^m, x) \mapsto \left(\mathrm{Exp}_{\varPhi} \sum_{i=1}^m a^i \xi_i \right) (x) \in \varPhi \right)$$

is a diffeomorphism onto its open image.

For the proof we need the following lemma which is known from theory of differential equations:

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LEMMA. If Z_1, \ldots, Z_m are some vector fields on the manifold M, then for any point $y_0 \in M$ there exist a neighbourhood W of y_0 and a cube

 $arOmega_K^m = \{(a^1,\, ...,\, a^m) \in R^m \colon \, |a^i| < K, \; i = 1,\, ...,\, m\}, \quad 0 < K < \infty,$

such that for each point $y \in W$ and $a \in \Omega_K^m$ there exists an integral curve

 $\varphi_{y,a} \colon I_2 \to M, \quad \varphi_{y,a}(0) = y,$

of the vector field $\sum_{i=1}^{m} a^{i} Z_{i}$, and the mapping

$$\varphi = \left(W \times I_2 \times \Omega_K^m \ni (y, t, a) \mapsto \varphi_{y, a}(t) \in M \right)$$

is smooth.

Proof of Theorem 3.2. From the above lemma it follows that for any point $x_0 \in U$ there exist neighbourhoods $U_m \subset \mathbb{R}^m$ of 0 and $U' \subset U$ of x_0 such that the mapping $\overline{\exp}_{\phi}$ is smooth. To prove the theorem it suffices to show that the differential $(\overline{\exp}_{\phi})_{*(0,x_0)}$ is an isomorphism. First, we shall prove that the differential at the point a = 0 of the mapping

$$\overline{\mathrm{Exp}}_{\varPhi}(x_0) = \left(U_m \ni (a^1, \ldots, a^m) \mapsto \left(\mathrm{Exp}_{\varPhi} \sum_{i=1}^m a^i \xi_i \right) (x_0) \in \varPhi_{x_0} \right)$$

is an isomorphism. Denote this mapping by \varkappa and identify the tangent spaces $T_0(R^m)$ and $T_{l_{x_0}}(\Phi_{x_0})$ with R^m by means of the following isomorphism:

$$\begin{split} T_0(R^m) &\ni \sum_{i=1}^m c^i e_i \mapsto (c^1, \, \dots, \, c^m) \in R^m, \\ T_{l_{x_0}}(\Phi_{x_0}) &\ni \sum_{i=1}^m c^i \, \xi'_i(l_{x_0}) \mapsto (e^1, \, \dots, \, c^m) \in R^m \end{split}$$

Then $\varkappa_{*0} = \mathrm{id}_{R^m}$. Indeed, if $b = (b^1, \ldots, b^m) \in R^m$ is an arbitrary point and $\lambda_b = (R \ni s \mapsto s \cdot b \in R^m)$, then

$$\varkappa_{*0}(b) = (\varkappa \circ \lambda_b)_{*0} \left(\frac{\partial}{\partial t} \bigg|_0 \right) = b$$

because $\varkappa \circ \lambda_b$ is an integral curve of the vector field $\sum_{i=1}^{m} b^i \xi'_i | \Phi_{x_0}$ and $\varkappa \circ \lambda_b(0) = x_0$. Now, the theorem is implied by the following fact:

If $p: P \to N$, $q: P' \to N$ are coregular mappings and $f: P \to P'$ is a mapping such that $q \circ f = p$, and $p_0 \in P$, $x_0 = p(p_0)$,

$$f_1 = f|p^{-1}[\{x_0\}]: P|p^{-1}[\{x_0\}] \to P'|q^{-1}[\{x_0\}],$$

and $(f_1)_{*p_0}$ is an isomorphism, then f_{*p_0} is also an isomorphism.

LIE GROUPOIDS

The mapping inverse to $\overline{\exp}_{\Phi}$ is called the *exponential coordinate* system determined by the cross-sections $\xi_1, \ldots, \xi_m \in C_0^{\infty}(i^*(T^a\Phi))$ which are a basis in a neighbourhood of $x \in M$.

COROLLARY. There exists an open set $\Omega \subset \Phi$ which contains all units and is contained in the set

$$E = \left\{ (\operatorname{Exp}_{\varphi} \xi)(x) \colon x \in M, \ \xi \in C_0^{\infty}(i^*(T^{\alpha} \Phi)) \right\}.$$

THEOREM 3.3. Let m and n be any subbundles of $i^*(T^a\Phi)$ such that $i^*(T^a\Phi) = \mathfrak{m} \oplus \mathfrak{n}$. Let $\xi_1, \ldots, \xi_m \in C_0^{\infty}(\mathfrak{m})$ and $\xi_{m+1}, \ldots, \xi_{m+n} \in C_0^{\infty}(\mathfrak{n})$ be cross-sections which are a basis of m and n, respectively, over a non-empty subset $U \subset M$. Then the cross-sections $\xi_1, \ldots, \xi_m, \xi_{m+1}, \ldots, \xi_{m+n}$ are a basis of $i^*(T^a\Phi)$ over U. Let $\overline{\mathrm{Exp}}_{\Phi}$ be defined for these sections. Then for each point $x \in U$ there exist neighbourhoods $U' \subset U$ of $x, U_m \subset \mathbb{R}^m$ of 0, and $U_n \subset \mathbb{R}^n$ of 0 such that the mapping

$$\lambda \colon U_m \times U_n \times U' \to \Phi$$

defined by

$$\lambda(a, b, y) = \operatorname{Exp}_{\phi}((a, 0), \beta \circ \overline{\operatorname{Exp}}_{\phi}((0, b), y)) \cdot \overline{\operatorname{Exp}}_{\phi}((0, b), y)$$

is a diffeomorphism onto its open image.

Proof. Let $\overline{\operatorname{Exp}}_{\varphi}$: $W \times U_1 \to \Phi$ be the diffeomorphism onto its open image Ω , where $W \subset \mathbb{R}^{m+n} = \mathbb{R}^m \times \mathbb{R}^n$ and $U_1 \subset U$ are open sets such that $0 \in W$ and $s \in U_1$.

Since λ is smooth, we can take neighbourhoods $U_m \subset \mathbb{R}^m$ of 0, $U_n \subset \mathbb{R}^n$ of 0, and $U' \subset U_1$ of x such that $\lambda[U_m \times U_n \times U'] \subset \Omega$. We denote by $(x^1(z), \ldots, x^{m+n}(z), a(z))$ the exponential coordinates of $z \in \Omega$. Then

$$x^i(\operatorname{Exp}_{\bullet}((a, 0), y)) = a^i, \quad i = 1, ..., m+n, y \in U, a \in W.$$

Let us take the mapping

 $t = (\overline{\operatorname{Exp}}_{\phi})^{-1} \circ \lambda \colon U_m \times U_n \times U' \to W \times U_1$

which is of the form

$$t(a, b, y) = (t_y(a, b), y).$$

To prove the theorem it suffices to show that the differential $(t_x)_{*(0,0)}$ is an isomorphism. For i = 1, ..., m+n we have

$$t_x^i(a^1, \ldots, a^m, b^1, \ldots, b^n) = x^i \left(\left(\operatorname{Exp}_{\varphi} \sum_{i=1}^m a^i \xi_i \right) \left(\beta \circ \left(\operatorname{Exp}_{\varphi} \sum_{i=1}^n b^i \xi_{m+i} \right) (x) \right) \cdot \left(\operatorname{Exp}_{\varphi} \sum_{i=1}^n b^i \xi_{m+i} \right) (x) \right).$$

Put

$$au_{i,j} = ig(I_s
i s \mapsto t^i_x(\underbrace{0,\ldots,0}_{j-1},s,0,\ldots,0) \in Rig) \quad ext{ for } i,j=1,\ldots,m+n,$$

where $\varepsilon > 0$ and $X_{i_{\varepsilon}} \subset U_{m} \times U_{n}$. Then $\tau_{i,j}(s) = s \cdot \delta_{j}^{i}$. Therefore, $t_{x|j}^{i}(0, 0) = \delta_{j}^{i}$ and

$$\det[t^{i}_{r|i}(0,0): i, j \leq m+n] = 1 \neq 0,$$

which completes the proof.

THEOREM 3.4. An injective homomorphism $F: \Phi \to \Phi'$ of the L.g.'s (1.2) is an immersion.

Proof. It is easy to prove that a homomorphism $F = \Phi \to \Phi'$ is an immersion if and only if \tilde{F}_* : $i^*(T^a \Phi) \to i'^*(T^a \Phi')$ is a monomorphism of the vector bundles. Let F be injective. We shall prove that \tilde{F}_* is a monomorphism. Let us take a vector $v \in i^*(T^a \Phi)$ such that $\tilde{F}_*(v) = 0$. Assume that $\xi \in C_0^o(i^*(T^a \Phi))$ is a cross-section for which $\xi(x) = v$. Then (Theorem 3.1)

$$(\operatorname{Exp}_{\phi} t(\tilde{F}_*\circ\xi))(x) = (F\circ\operatorname{Exp}_{\phi} t\xi)(x).$$

Since $\tilde{F}_* \circ \xi(x) = \tilde{F}_*(v) = 0$, we have $(\tilde{F}_* \circ \xi)'(l_x) = 0$. Hence the integral curve of $(\tilde{F}_* \circ \xi)'$ passing through l_x is constant, and since $t \mapsto (\operatorname{Exp}_{\sigma'} t(\tilde{F}_* \circ \xi))(x)$ is such a curve, we obtain

$$(\operatorname{Exp}_{\bullet} t(\bar{F}_* \circ \xi))(x) = l_x.$$

Consequently, $F((\exp_{\phi} t\xi)(x)) = l_x$, and from the injectivity of *F* we get $(\exp_{\phi} t\xi)(x) = l_x$. Since $t \mapsto (\exp_{\phi} t\xi)(x)$ is an integral curve of ξ' , we have $v = \xi(x) = \xi'(l_x) = 0$.

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